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CS 290  
Host-based Security and Malware

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# Reverse Engineering

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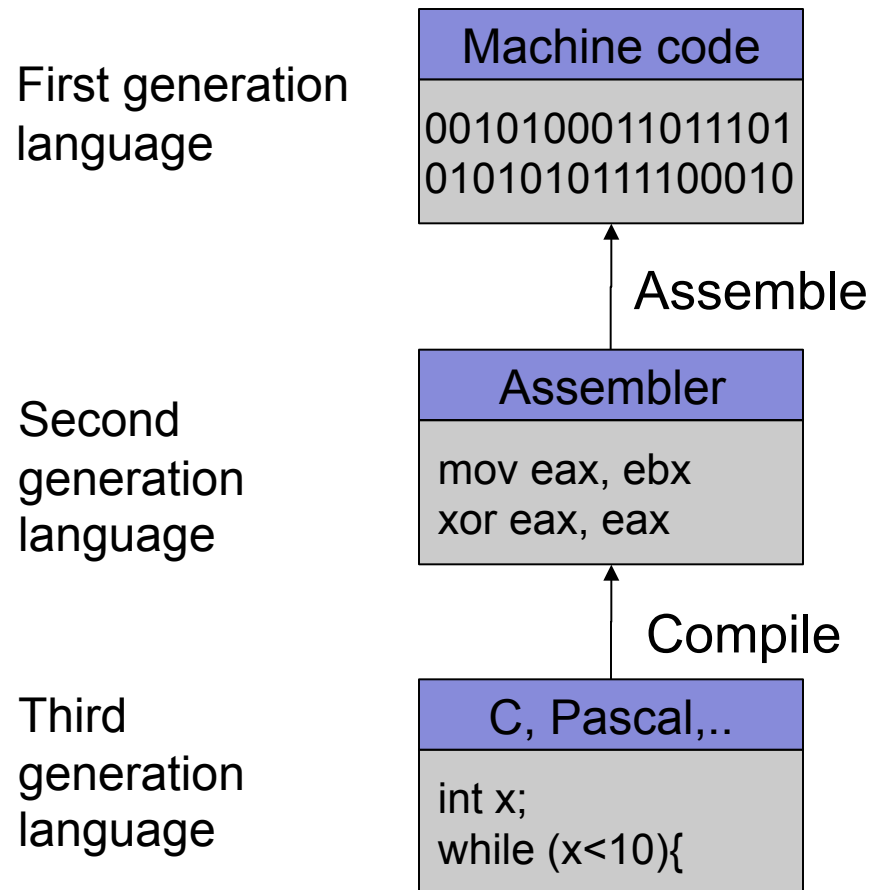
# Introduction

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- Reverse engineering
  - process of analyzing a system
  - understand its structure and functionality
  - used in different domains (e.g., consumer electronics)
- Software reverse engineering
  - understand architecture (from source code)
  - extract source code (from binary representation)
  - change code functionality (of proprietary program)
  - understand message exchange (of proprietary protocol)

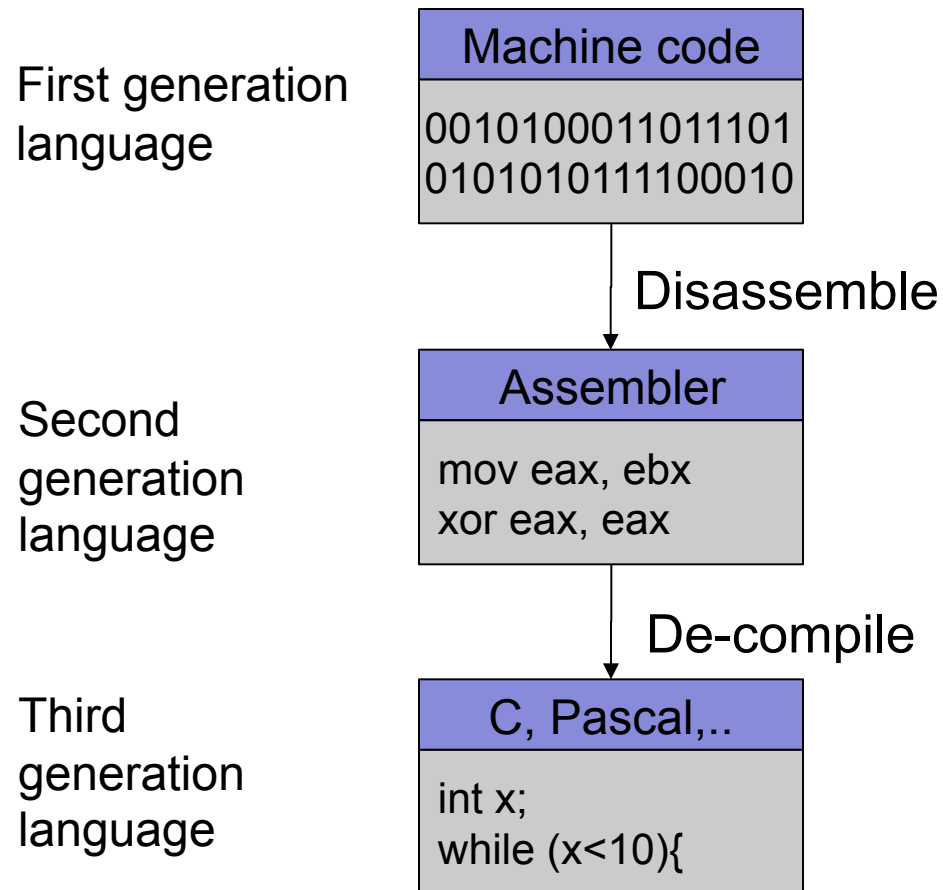
# Software Engineering

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# Software Reverse Engineering

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# Going Back is Hard!

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- Fully-automated disassemble/de-compilation of arbitrary machine-code is theoretically an undecidable problem
- Disassembling problems
  - hard to distinguish code (instructions) from data
- De-compilation problems
  - structure is lost
    - data types are lost, names and labels are lost
  - no one-to-one mapping
    - same code can be compiled into different (equivalent) assembler blocks
    - assembler block can be the result of different pieces of code

# Why Reverse Engineering

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- Software interoperability
  - Samba (SMB Protocol)
  - OpenOffice (MS Office document formats)
- Emulation
  - Wine (Windows API)
  - React-OS (Windows OS)
- Malware analysis
- Program cracking
- Compiler validation

# Analyzing a Binary

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## Static Analysis

- Identify the file type and its characteristics
  - architecture, OS, executable format...
- Extract strings
  - commands, password, protocol keywords...
- Identify libraries and imported symbols
  - network calls, file system, crypto libraries
- Disassemble
  - program overview
  - finding and understanding important functions
    - by locating interesting imports, calls, strings...



# Analyzing a Binary

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## Dynamic Analysis

- Memory dump
  - extract code after decryption, find passwords...
- Library/system call/instruction trace
  - determine the flow of execution
  - interaction with OS
- Debugging running process
  - inspect variables, data received by the network, complex algorithms..
- Network sniffer
  - find network activities
  - understand the protocol

# Static Techniques

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- Gathering program information
  - get some rough idea about binary (file)

```
linux util # file sil
sil: ELF 32-bit LSB executable, Intel 80386, version 1
(SYSV), for GNU/Linux 2.6.9, dynamically linked (uses s
hared libs), not stripped
```

- strings that the binary contains (strings)

```
linux util # strings sil | head -n 5
/lib/ld-linux.so.2
_Jv_RegisterClasses
__gmon_start__
libc.so.6
puts
```

# Static Techniques

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- Examining the program (ELF) header (`elfsh`)

```
[ELF HEADER]
[Object sil, MAGIC 0x464C457F]
```

```
Architecture      : Intel 80386      ELF Version       : 1
Object type       : Executable object SHT strtab index  : 25
Data encoding     : Little endian   SHT foffset      : 4061
PHT foffset       : 52              SHT entries number : 28
PHT entries number : 8              SHT entry size    : 40
PHT entry size    : 32              ELF header size   : 52
Entry point       : 0x8048500       [_start]
{PAX FLAGS = 0x0}
PAX_PAGEEXEC     : Disabled        PAX_EMULTRAMP    : Not emulated
PAX_MPROTECT     : Restricted      PAX_RANMMAP     : Randomized
PAX_RANDEXEC     : Not randomized  PAX_SEGMEEXEC   : Enabled
```

Program entry point



# Static Techniques

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- Used libraries

Interesting “shared” library –  
used for (fast) system calls

- easier when program is dynamically linked (ldd)

```
linux util # ldd sil
linux-gate.so.1 => (0xffffe000)
libc.so.6 => /lib/libc.so.6 (0xb7e99000)
/lib/ld-linux.so.2 (0xb7fcf000)
```

- more difficult when program is statically linked

```
linux util # gcc -static -o sil-static simple.c
linux util # ldd sil-static
not a dynamic executable
linux util # file sil-static
sil-static: ELF 32-bit LSB executable, Intel 80386, version 1
(SYSV), for GNU/Linux 2.6.9, statically linked, not stripped
```

# Static Techniques

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## Looking at linux-gate.so.1

```
linux util # cat /proc/self/maps | tail -n 1
ffffe000-ffffff00 r-xp 00000000 00:00 0          [vdso]
linux util # dd if=/proc/self/mem of=linux-gate.dso bs=4096 skip=1048574
count=1 2> /dev/null
linux util # objdump -d linux-gate.dso | head -n 11

linux-gate.dso:      file format elf32-i386

Disassembly of section .text:

ffffe400 <__kernel_vsyscall>:
ffffe400:      51                push   %ecx
ffffe401:      52                push   %edx
ffffe402:      55                push   %ebp
ffffe403:      89 e5             mov    %esp,%ebp
ffffe405:      0f 34             sysenter
```

# Static Techniques

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- Used library functions
  - again, easier when program is dynamically linked (`nm -D`)

```
linux util # nm -D sil | tail -n8
          U fprintf
          U fwrite
          U getopt
          U opendir
08049bb4 B optind
          U puts
          U readdir
08049bb0 B stderr
```

- more difficult when program is statically linked

```
linux util # nm -D sil-static
nm: sil-static: No symbols
linux util # ls -la sil*
-rwxr-xr-x 1 root chris 8017 Jan 21 20:37 sil
-rwxr-xr-x 1 root chris 544850 Jan 21 20:58 sil-static
```

# Static Techniques

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## Recognizing libraries in statically-linked programs

- Basic idea
  - create a checksum (hash) for bytes in a library function
- Problems
  - many library functions (some of which are very short)
  - variable bytes – due to dynamic linking, load-time patching, linker optimizations
- Solution
  - more complex pattern file
  - uses checksums that take into account variable parts
  - implemented in `IDA Pro` as:  
Fast Library Identification and Recognition Technology (FLIRT)

# Static Techniques

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- Program symbols
  - used for debugging and linking
  - function names (with start addresses)
  - global variables
  - use `nm` to display symbol information
  - most symbols can be removed with `strip`
- Function call trees
  - draw a graph that shows which function calls which others
  - get an idea of program structure



# Static Techniques

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## Displaying program symbols

```
linux util # nm sil | grep " T"  
080488c7 T __i686.get_pc_thunk.bx  
08048850 T __libc_csu_fini  
08048860 T __libc_csu_init  
08048904 T _fini  
08048420 T _init  
08048500 T _start  
080485cd T display_directory  
080486bd T main  
080485a4 T usage  
linux util # strip sil  
linux util # nm sil | grep " T"  
nm: sil: no symbols
```

# Static Techniques

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- Disassembly
  - process of translating binary stream into machine instructions
- Different level of difficulty
  - depending on ISA (instruction set architecture)
- Instructions can have
  - fixed length
    - more efficient to decode for processor
    - RISC processors (SPARC, MIPS)
  - variable length
    - use less space for common instructions
    - CISC processors (Intel x86)

# Static Techniques

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- Fixed length instructions
  - easy to disassemble
  - take each address that is multiple of instruction length as instruction start
  - even if code contains data (or junk), all program instructions are found
- Variable length instructions
  - more difficult to disassemble
  - start addresses of instructions not known in advance
  - different strategies
    - linear sweep disassembler
    - recursive traversal disassembler
  - disassembler can be desynchronized with respect to actual code

# Intel x86 Assembler Primer

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- Assembler Language
  - human-readable form of machine instructions
  - must understand the hardware architecture, memory model, and stack
- AT&T syntax
  - `mnemonic source(s), destination`
  - standalone numerical constants are prefixed with a `$`
  - hexadecimal numbers start with `0x`
  - registers are specified with `%`

# Intel x86 Assembler Primer

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- Registers

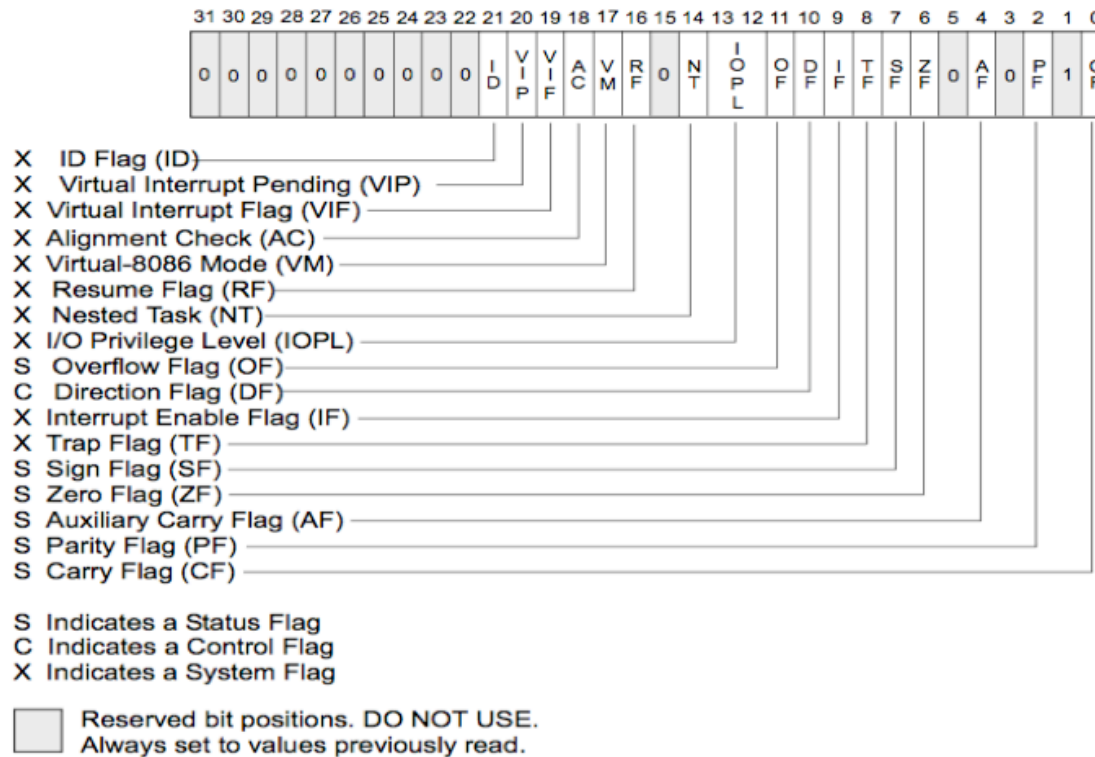
- local variables of processor
- six 32-bit general purpose registers
  - can be used for calculations, temporary storage of values, ...  
`%eax, %ebx, %ecx, %edx, %esi, %edi`
- several 32-bit special purpose registers
  - `%esp` – stack pointer
  - `%ebp` – frame pointer
  - `%eip` – instruction pointer

- Important mnemonics (instructions)

|                         |  |
|-------------------------|--|
| <code>mov</code>        | data transfer  |
| <code>add / sub</code>  | arithmetic   |
| <code>cmp / test</code> | compare two values and set control flags             |
| <code>je / jne</code>   | conditional jump depending on control flags (branch) |
| <code>jmp</code>        | unconditional jump                                   |

# Intel x86 Assembler Primer

## Status (EFLAGS) Register



# Intel x86 Assembler Primer

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- Status (EFLAGS) Register
  - used for control flow decision
  - set implicit by many operations (arithmetic, logic)
- Flags typically used for control flow
  - CF (carry flag)
    - set when operation “carries out” most significant bit
  - ZF (zero flag)
    - set when operation yields zero
  - SF (signed flag)
    - set when operation yields negative result
  - OF (overflow flag)
    - set when operation causes 2’s complement overflow
  - PF (parity flag)
    - set when the number of ones in result of operation is even

# Intel x86 Assembler Primer

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| Instruction                                    | Synonym                    | Jump condition  | Description  |
|--|----------------------------|---|--|
| jmp label<br>jmp *operand                      |                            | 1<br>1  | direct jump<br>indirect jump   |
| je label<br>jne label                          | jz<br>jnz                  | ZF<br>~ZF   | equal/zero<br>not equal/zero   |
| js label<br>jns label                          |                            | SF<br>~SF   | negative<br>non-negative   |
| jg label<br>jge label<br>jl label<br>jle label | jnle<br>jnl<br>jnge<br>jng | ~(SF ^ OF) & ~ZF<br>(~SF ^ OF)<br>SF ^ OF<br>(SF ^ OF)   ZF | greater than (signed)<br>greater or equal (signed)<br>less than (signed)<br>less or equal (signed) |
| ja label<br>jae label<br>jb label<br>jbe label | jnbe<br>jnb<br>jnae<br>jna | ~CF & ~ZF<br>~CF<br>CF<br>CF   ZF                           | above (unsigned)<br>above or equal (unsigned)<br>below (unsigned)<br>below or equal (unsigned)     |



# Intel x86 Assembler Primer

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- When are flags set?
  - implicit, as a side effect of many operations
  - can use explicit compare / test operations
- Compare
  - `cmp b, a` [ note the order of operands ]
  - computes (a – b) but does not overwrite destination
  - sets ZF (if a == b), SF (if a < b) [ and also OF and CF ]
- How is a branch operation implemented
  - typically, two step process
  - first, a compare/test instruction
  - followed by the appropriate jump instruction

# Intel x86 Assembler Primer

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- Program can access data stored in memory
  - memory is just a linear (flat) array of memory cells (bytes)
  - accessed in different ways (called addressing modes)
- Most general fashion
  - `address: displacement(%base, %index, scale)`  
where the result address is `displacement + %base + %index*scale`
- Simplified variants are also possible
  - use only displacement → direct addressing
  - use only single register → register addressing

# Intel x86 Assembler Primer

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- Stack
  - managed by stack pointer (%esp) and frame pointer (%ebp)
  - special commands (push, pop)
  - used for
    - function arguments
    - function return address
    - local arguments
- Byte ordering
  - important for multi-byte values (e.g., four byte long value)
  - Intel uses *little endian* ordering
  - how to represent 0x03020100 in memory?

|       |   |
|-------|---|
| 0x040 | 0 |
| 0x041 | 1 |
| 0x042 | 2 |
| 0x043 | 3 |

# Intel x86 Assembler Primer

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```
# no input
# returns a status code, you can view it by typing echo $?
# %ebx holds the return code

.section .data
.section .text
.globl _start

_start:
mov $1, %eax      # This is the system call for exiting program
movl $0, %ebx     # This value is returned as status
int $0x80         # This interrupt calls the kernel, to execute sys call
```

# Intel x86 Assembler Primer

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- So how do we create the application?
  - we need to assemble and link the code
  - this can be done by using the assembler *as* (or *gcc*)

- Assemble

```
as exit.s -o exit.o |  
gcc -c -o exit.o exit.s
```

- Link

```
ld -o exit exit.o |  
gcc -nostartfiles -o exit exit.o
```

# Intel x86 Assembler Primer

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## Task: Find the maximum of a list of numbers

- Questions to ask:
  - Where will the numbers be stored?
  - How do we find the maximum number?
  - How much storage do we need?
  - Will registers be enough or is memory needed?
  
- Let us designate registers for the task at hand:
  - %edi holds position in list
  - %ebx will hold current highest
  - %eax will hold current element examined

# Intel x86 Assembler - Algorithm

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- Check if `%eax` is zero (i.e., termination sign)
  - if yes, exit
  - if not, increase current position `%edi`
- Load next value in the list to `%eax`
  - we need to think about what addressing mode to use here
- Compare `%eax` (current value) with `%ebx` (highest value so far)
  - if the current value is higher, replace `%ebx`
- Repeat

# Intel x86 Assembler - Code

---

```
.section .data
    data_items:
        .long 3,67,34,222,45,75,54,34,44,33,22,11,66,0

.section .text
.globl _start

_start:
    movl    $0, %edi        # Reset index
    movl    data_items(,%edi,4), %eax
    movl    %eax, %ebx      #First item is the biggest so far
```



# Intel x86 Assembler - Code

---

```
start_loop:
    cmpl    $0, %eax
    je      loop_exit
    incl    %edi          # Increment edi
    movl    data_items(,%edi,4), %eax    # Load the next value
    cmpl    %ebx, %eax    # Compare ebx with eax
    jle    start_loop    # If it is less, just jump to the beginning
    movl    %eax, %ebx    # Otherwise, store the new largest number
    jmp    start_loop

loop_exit:
    movl    $1, %eax      # Remember the exit sys call? It is 1
    int    $0x80
```

# Intel x86 Assembler Primer

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- If statement

```
#include <stdio.h>

int main(int argc, char **argv)
{
    int a;

    if(a < 0) {
        printf("A < 0\n");
    }
    else {
        printf("A >= 0\n");
    }
}
```

```
.LC0:
    .string "A < 0\n"

.LC1:
    .string "A >= 0\n"

.globl main
.type   main, @function

main:
    [ function prologue ]
    cmpl    $0, -4(%ebp) /* compute: a - 0 */
    jns     .L2          /* jump, if sign bit
                        not set: a >= 0 */

    movl    $.LC0, (%esp)
    call    printf
    jmp     .L3

.L2:
    movl    $.LC1, (%esp)
    call    printf

.L3:
    leave
    ret
```

# Intel x86 Assembler Primer

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- While statement

```
#include <stdio.h>

int main(int argc, char **argv)
{
    int i;

    i = 0;
    while(i < 10)
    {
        printf("%d\n", i);
        i++;
    }
}
```

```
.LC0:
    .string "%d\n"

main:
    [ function prologue ]
    movl    $0, -4(%ebp)

.L2:
    cmpl   $9, -4(%ebp)
    jle    .L4
    jmp    .L3

.L4:
    movl   -4(%ebp), %eax
    movl   %eax, 4(%esp)
    movl   $.LC0, (%esp)
    call   printf
    leal   -4(%ebp), %eax
    incl   (%eax)
    jmp    .L2

.L3:
    leave
    ret
```

# Static Techniques

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... after this x86 assembler digression, back to disassembling

- Linear sweep disassembler
  - start at beginning of code (.text) section
  - disassemble one instruction after the other
  - assume that well-behaved compiler tightly packs instructions
  - `objdump -d` uses this approach

# Static Techniques

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- Recursive traversal disassembler
  - aware of control flow
  - start at program entry point (e.g., determined by ELF header)
  - disassemble one instruction after the other, until branch or jump is found
  - recursively follow both (or single) branch (or jump) targets
  - not all code regions can be reached
    - indirect calls and indirect jumps
    - use a register to calculate target during run-time
  - for these regions, linear sweep is used
  - IDA `Pro` uses this approach

# Dynamic Techniques

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- General information about process
  - `/proc` file system
  - `/proc/<pid>/` for a process with pid `<pid>`
  - interesting entries
    - `cmdline` (show command line)
    - `environ` (show environment)
    - `maps` (show memory map)
    - `fd` (file descriptor to program image)
- Interaction with the environment
  - file system
  - network

# Dynamic Techniques

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- File system interaction
  - `lsdf`
  - lists all open files associated with processes
- Windows Registry
  - `regmon` (Sysinternals)
- Network interaction
  - check for open ports
    - processes that listen for requests or that have active connections
    - `netstat`
    - also shows UNIX domain sockets used for IPC
  - check for actual network traffic
    - `tcpdump`
    - `ethereal`

# Dynamic Techniques

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- System calls
  - are at the boundary between user space and kernel
  - reveal much about a process' operation
  - `strace`
  - powerful tool that can also
    - follow child processes
    - decode more complex system call arguments
    - show signals
  - works via the `ptrace` interface
- Library functions
  - similar to system calls, but dynamically linked libraries
  - `ltrace`



# Dynamic Techniques

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- Execute program in a controlled environment
  - sandbox / debugger
- Advantages
  - can inspect actual program behavior and data values
  - (at least one) target of indirect jumps (or calls) can be observed
- Disadvantages
  - may accidentally launch attacks
  - anti-debugging mechanisms
  - not all possible traces can be seen

# Dynamic Techniques

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- Debugger
  - breakpoints to pause execution
    - when execution reaches a certain point (address)
    - when specified memory is access or modified
  - examine memory and CPU registers
  - modify memory and execution path
- Advanced features
  - attach comments to code
  - data structure and template naming
  - track high level logic
    - file descriptor tracking
  - function fingerprinting

# Dynamic Techniques

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- Debugger on x86 / Linux
  - use the `ptrace` interface
- `ptrace`
  - allows a process (parent) to monitor another process (child)
  - whenever the child process receives a signal, the parent is notified
  - parent can then
    - access and modify memory image (peek and poke commands)
    - access and modify registers
    - deliver signals
  - `ptrace` can also be used for system call monitoring

# Dynamic Techniques

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- Breakpoints
  - hardware breakpoints
  - software breakpoints
- Hardware breakpoints
  - special debug registers (e.g., Intel x86)
  - debug registers compared with PC at every instruction
- Software breakpoints
  - debugger inserts (overwrites) target address with an `int 0x03` instruction
  - interrupt causes signal SIGTRAP to be sent to process
  - debugger
    - gets control and restores original instruction
    - single steps to next instruction
    - re-inserts breakpoint

# Challenges

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- Reverse engineering is difficult by itself
  - a lot of data to handle
  - low level information
  - creative process, experience very valuable
  - tools can only help so much
- Additional challenges
  - compiler code optimization
  - code obfuscation
  - anti-disassemble techniques
  - anti-debugging techniques

# Anti-Disassembly

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- Against static analysis (disassembler)
- Confusion attack
  - targets linear sweep disassembler
  - insert data (or junk) between instructions and let control flow jump over this garbage
  - disassembler gets desynchronized with true instructions

```
jmp Label1          | 8048000: 74 02          | je 8048004
.short  0x4711     | 8048002: 47             | inc    %edi
                | 8048003: 11 90 90 90 90 90 | adc %edx,0x90909090(%eax)
Label1:          | 8048004:              | <Label1>
```

# Anti-Disassembly

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- Advanced confusion attack
  - targets recursive traversal disassembler
  - replace direct jumps (calls) by indirect ones (branch functions)
  - force disassembler to revert to linear sweep, then use previous attack

# Anti-Debugging

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- Against dynamic analysis (debugger)

- detect tracing

- a process can be traced only once

```
if (ptrace(PTRACE_TRACEME, 0, 1, 0) < 0)
    exit(1);
```

- detect breakpoints

- look for int 0x03 instructions

```
if ((* (unsigned *) ((unsigned)<addr>+3) & 0xff) == 0xcc)
    exit(1);
```

- checksum the code

```
if (checksum(text_segment) != valid_checksum)
    exit(1);
```



# Reverse Engineering

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- Goals
  - focused exploration
  - deep understanding
- Case study
  - copy protection mechanism
  - program expects name and serial number
  - when serial number is incorrect, program exits
  - otherwise, we are fine
- Changes in the binary
  - can be done with `hexedit`

# Reverse Engineering

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- Focused exploration
  - *bypass check routines*
  - locate the point where the failed check is reported
  - find the routine that checks the password
  - find the location where the results of this routine are used
  - slightly modify the jump instruction
- Deep understanding
  - *key generation*
  - locate the checking routine
  - analyze the disassembly
  - run through a few different cases with the debugger
  - understand what check code does and develop code that creates appropriate keys

# Malicious Code Analysis

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## *Static analysis vs. dynamic analysis*

- Static analysis
  - code is not executed
  - all possible branches can be examined (in theory)
  - quite fast
- Problems of static analysis
  - undecidable in general case, approximations necessary
  - binary code typically contains very little information
    - functions, variables, type information, ...
  - disassembly difficult (particularly for Intel x86 architecture)
  - obfuscated code, packed code
  - self-modifying code

# Malicious Code Analysis

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- Dynamic analysis
  - code is executed
  - sees instructions that are actually executed
- Problems of dynamic analysis
  - single path (execution trace) is examined
  - analysis environment possibly not *invisible*
  - analysis environment possibly not *comprehensive*
- Possible analysis environments
  - instrument program
  - instrument operating system
  - instrument hardware

# Malicious Code Analysis

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- Instrument program
  - analysis operates in same address space as sample
  - manual analysis with debugger
  - Detours (Windows API hooking mechanism)
  
  - binary under analysis is modified
    - breakpoints are inserted
    - functions are rewritten
    - debug registers are used
  - not invisible, malware can detect analysis
  - can cause significant manual effort

# Malicious Code Analysis

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- Instrument operating system
  - analysis operates in OS where sample is run
  - Windows system call hooks
  - invisible to (user-mode) malware
  - can cause problems when malware runs in OS kernel
  - limited visibility of activity inside program
    - cannot set function breakpoints
- Virtual machines
  - allow to quickly restore analysis environment
  - might be detectable (x86 virtualization problems)

# Malicious Code Analysis

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- Instrument hardware
  - provide virtual hardware (processor) where sample can execute (sometimes including OS)
  - software emulation of executed instructions
  - analysis observes activity “from the outside”
  
  - completely transparent to sample (and guest OS)
  - operating system environment needs to be provided
  - limited environment could be detected, but faster
  - complete environment is comprehensive, but slower
  
  - Anubis uses this approach

# Semantic Gap

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- Analysis observes activity “from the outside”
  - how to relate instructions executed on processor with activity inside the operating system and sample?
  - must encode some knowledge about guest OS and processes
    - we chose to target MS Windows on Intel x86 machines
  - Qemu used as emulation environment
- Questions
  - how to identify which instructions belong to malware sample?
  - what to analyze?
  - how to implement analysis?



# Tracking Malware Process

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- Executed instructions must be assigned to correct process
  - make use of CR3 register
    - control register used for virtual memory management
    - holds physical address of the base of the page directory
    - unique for each process
    - ensures that virtual address spaces are disjoint
  - reloaded at every context switch
- Obtaining value of CR3 register
  - use small component inside operating system
  - extracts value from kernel task structure (EPROCESS)
  - process started in suspended state

# Analysis Information

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- Process interacts with operating system via system calls
  - needs OS for every interaction with environment
    - file system, network, registry, ...
  - monitor system calls
  - unfortunately, on Windows, system calls largely undocumented and can change without notice
  - developers are supposed to use Windows API, which denotes a collection of stable, user-mode, shared libraries
  - of course, Windows API can be bypassed
  
- we monitor Windows API calls and NT kernel calls

# Analysis Report

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- File activity
  - read, write, create, open, ...
- Registry activity
- Service activity
  - start or stop of Windows services (via Service Manager)
- Process activity
  - start, terminate process, inter-process communication
- Network activity
  - API calls and packet logs

# Analysis Implementation

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- Windows API and kernel calls must be hooked *without* interfering with the program (and its memory)
- Can be implemented in straightforward fashion
  - compare address of instruction executed with function start address
  - Qemu allows to do this efficiently
  - start addresses extracted from library export tables
- Arbitrary addresses are possible
  - analysis has fine-grain control

# Analysis Implementation

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- Information about function invocation alone insufficient
  - we also want to know about arguments
- Callback invoked when “breakpoint” reached
  - allows us to extract argument values
  - semantic gap again, Anubis only knows about physical address space
  - appropriate read functions require argument type information (structure and size of arguments), similar to advanced debuggers
  - would be tedious to write by hand, automatic support desirable
- Callbacks are invoked on function call and function return

# Argument Extraction

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- Generate routines to extract argument values automatically
  - provide values directly to callback routine
  - requires knowledge about argument types
- Code generation component
  - processes Windows header files (read type definitions)
  - parameters may be in and out parameters (or both)
  - parameters may be of unknown length
    - zero-terminated strings
    - arrays where second parameters specifies length
  - headers files were manually augmented
  - complex structures (with pointers) are traversed automatically

# Argument Extraction

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- Problem
  - not all argument values need to be present in physical memory
  - Anubis has only access to (emulated) physical memory
  - argument values could be swapped out
  - other problems are shared libraries that are not paged in
    - e.g., due to lazy evaluation
- Solution
  - make process access virtual address(es)
  - forces Windows to bring in memory (page fault handler)
  - Anubis has to (transparently) inject such access into process

# Code Injection

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- Modify control flow of target process
  - necessary to bring in paged out memory content
  - but also useful for calling arbitrary functions in context of target
- Calling functions
  - distinguish between open and create file (or registry key)
  - distinguish between files and directories
  - resolve unknown handles
- Can be easily done with Qemu
  - without modifying process' code
  - only problem is to push argument values onto process stack
  - dual problem to reading arguments, generator can be reused



# Stealthiness

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- One obvious difference between machine and emulator
  - time of execution
- Time could be used to detect our system
  - emulation allows to address these issues
  - certain instructions can be dynamically modified to return innocently looking results
  - for example, RTC (real-time clock) - RTDSC instruction