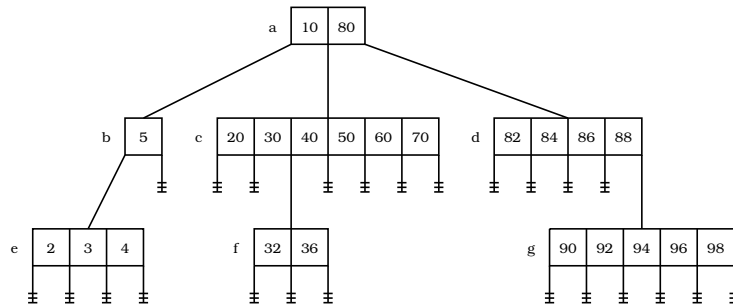


***m*-way Search Trees**

m-way Search Tree: Empty, or if not empty then:

- Each internal node has q children and $q - 1$ elements, for $2 \leq q \leq m$.
- Nodes with p elements have exactly $p + 1$ children.
- Suppose a node has p elements. Let $k_1, k_2, \dots, k_p$ be the keys of these elements. Then $k_1 < k_2 < \dots < k_p$. Let $c_0, c_1, \dots, c_p$ be the $p + 1$ children of the node.
 - The elements in the subtree with root c_0 have keys smaller than k_1 .
 - The elements in the subtree rooted at c_i have keys larger than k_i and smaller than k_{i+1} , $1 \leq i < p$.
 - The elements in the subtree rooted at c_p have keys larger than k_p .

Example



- a: 2,b,(10,c),(80,d)
- b: 1,e,(5,0)
- c: 6,0,(20,0),(30,f),(40,0),(50,0),(60,0),(70,0)
- d: 4,0,(82,0),(84,0),(86,0),(88,g)
- e: 3,0,(2,0),(3,0),(4,0)
- f: 2,0,(32,0),(36,0)
- g: 5,0,(90,0),(92,0),(94,0),(96,0),(98,0)
- Searching; Inserting (31,65);
- Deleting (20,84,5,10);
- Format $(n, c_0, (e_1, c_1), (e_2, c_2), \dots, (e_n, c_n))$

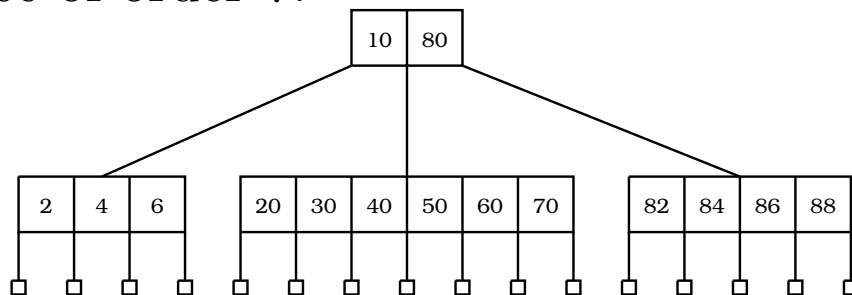
B-Trees of Order $m > 2$

(Different from textbook [W])

A B-Tree of order m is an m -way search tree. If the B-tree is not empty, the corresponding extended tree satisfies the following properties:

- The root has at least two children.
- All internal nodes other than the root have at least $\lceil m/2 \rceil$ children.
- All external nodes are at the same level.

A B-tree of order 7.



Properties

- $m > 2$ because they cannot represent all possible sets.
- B-Tree of order 3 is a 2-3 tree.
- B-Tree of order 4 is a 2-3-4 tree (Same as RB-Tree).

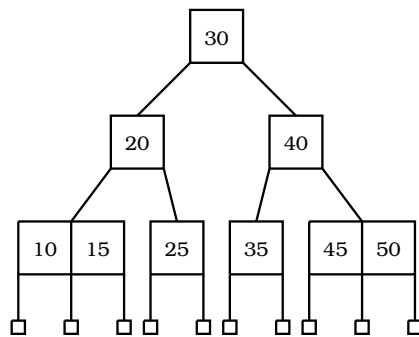
Lemma 11.3: Let T be a B-tree of order m and height h . Let $d = \lceil m/2 \rceil$ and let n be the number of elements in T .

1. $2d^{h-1} - 1 \leq n \leq m^h - 1$
2. $\log_m(n + 1) \leq h \leq \log_d(\frac{n+1}{2}) + 1$.

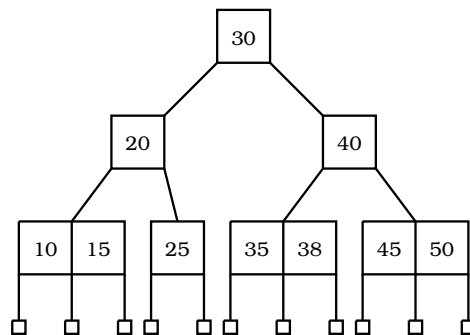
Proof: (1) $\Rightarrow$ (2). (1) follows from the fact that the minimum number of nodes on levels 1, 2, 3, 4, ..., h is 1, 2, $2d$, $2d^2$, ..., $2d^{h-2}$, and the maximum num. is 1, m , m^2 , ..., m^{h-1} . The number of null pointers = $n + 1$.

- A B-tree of order 200 and height 3 has at least 19,999 elements and therefore can represent all UCSB students.
- A B-tree of order 200 and height 5 has at least 199,999,999 and therefore can represent all U.S. voters.
- The order of a B-Tree is determined by the disk block size and size of individual elements.
- For obvious reasons all the B-tree examples have small order.
- Searching is like in an m -way search tree.

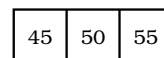
Insert Example (B-Tree of Order 3)



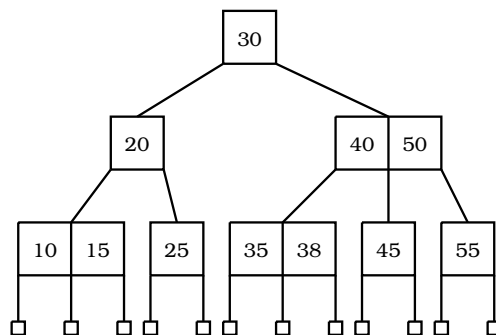
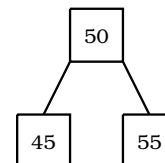
I 38



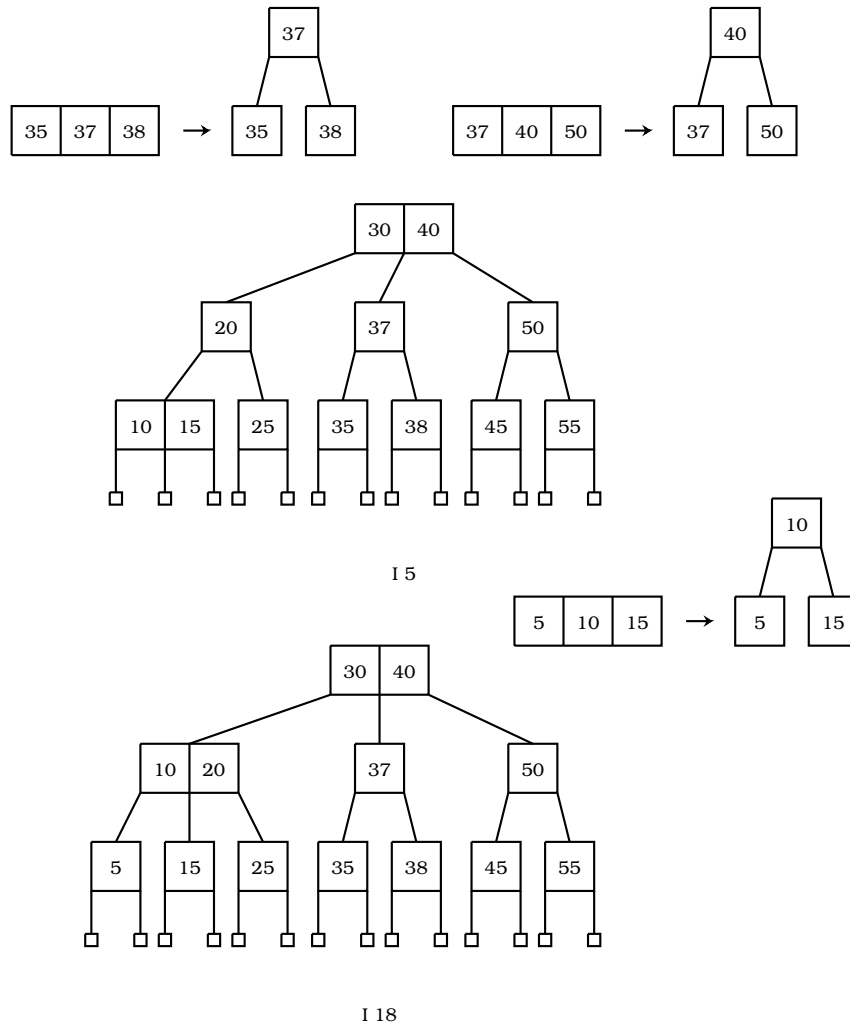
I 55

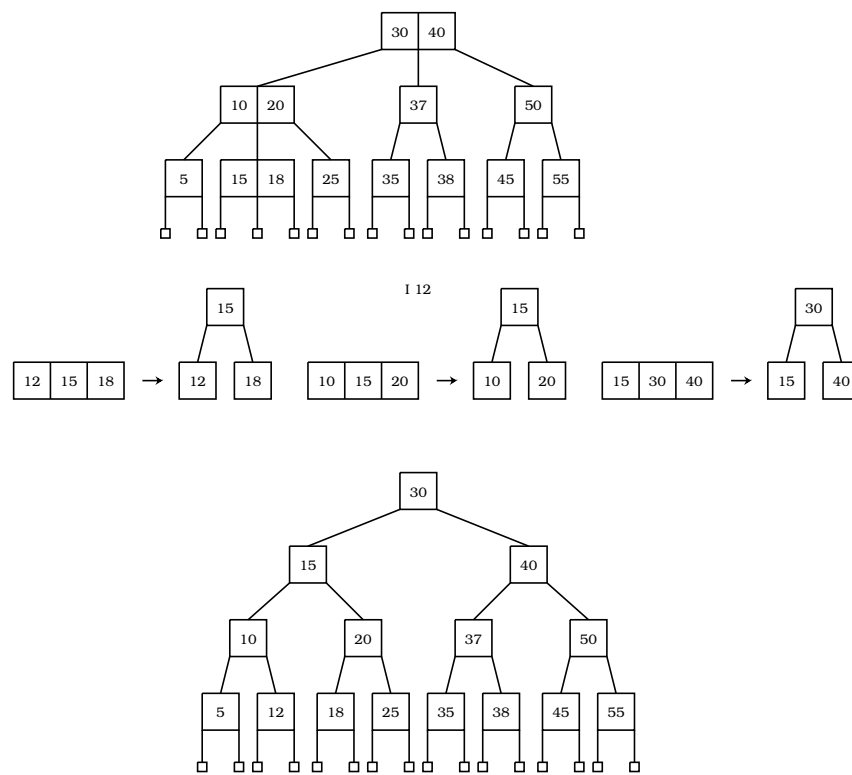


→



I 37





Insertion

Nodes are of the form $n, c_0, (e_1, c_1), \dots, (e_n, c_n)$, where the e 's are the values or keys and the c 's are the pointers.

Procedure `Insert(t,e)` { // t points to root, and e will be inserted

`c = NULL;` // (e,c) is to be inserted in leaf node

`Search(t,e,P,found);` // returns `found=true` if e in the tree

// and P will point to the node in main memory that has e ;

// Returns false if e is not in the B-tree and P will point

// to the last node visited (leaf node) during the search;

`Done = false;`

if not found {

while $P \neq \text{NULL}$ & not Done do

{Insert (c,e) into appropriate position in node P ;

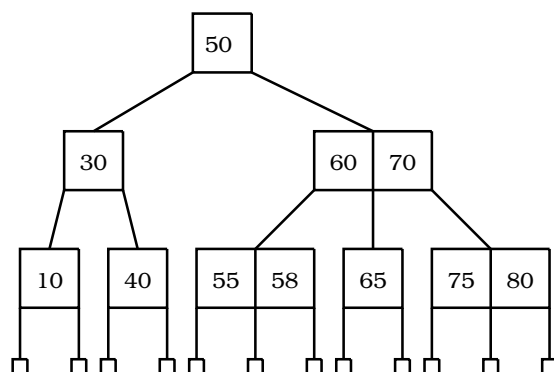
Let the resulting node be $P \rightarrow n, c_0, (e_1, c_1), \dots, (e_n, c_n)$

```

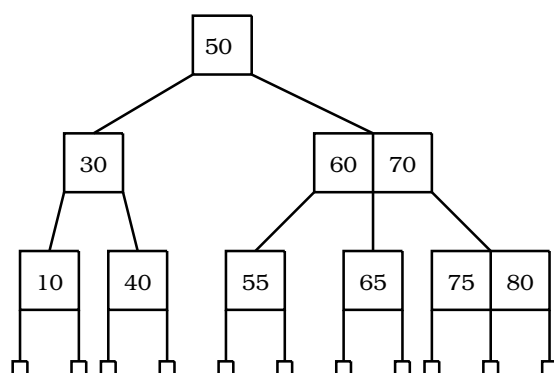
    if P->n <= m-1 {Output P to Disk; Done = true;}
    else { e = P->e_{ceil(m/2)};
          d = ceil(m/2);
          Split P into two nodes (in main memory)
          P: d-1,c_0,(e_1,c_1),...,(e_{d-1},c_{d-1})
          Q: m-d,c_d,(e_{d+1},c_{d+1}),...,(e_m,c_m)
          Output P and Q to Disk;
          c = Q;
          P = Parent(P); // Parent may be obtained from a
                        // stack that is built by the Search procedure;
        }
    }
if not Done { Create new node Q in memory;
              Q: 1,t,(e,c);
              t = Q;
              Output t to Disk;
            }
}
}

```

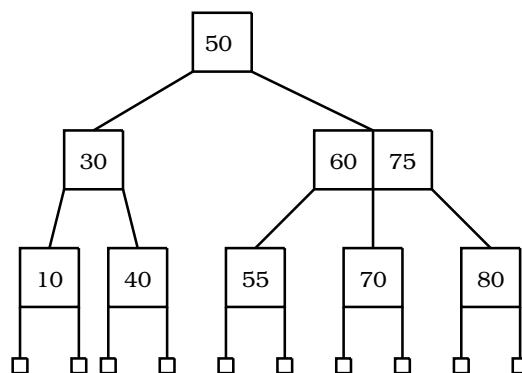
Delete Example



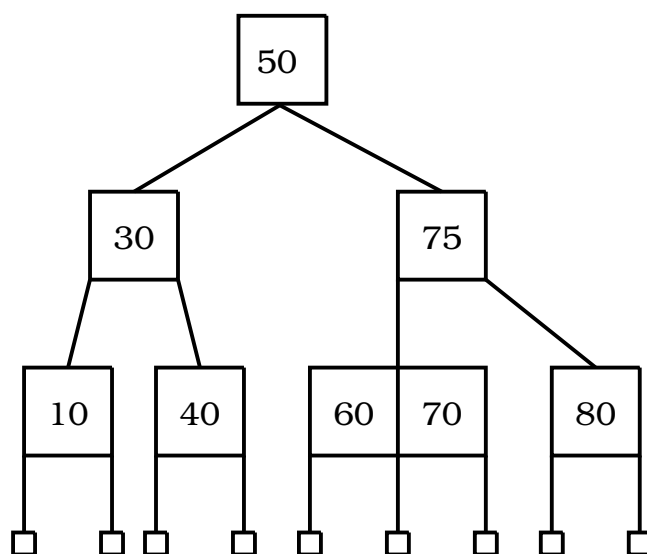
D 58



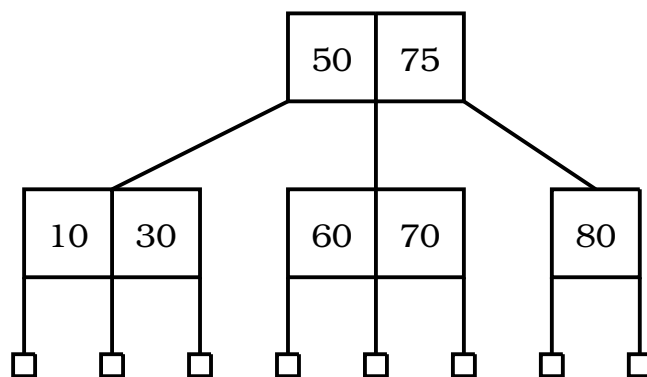
D 65



D 55



D 40



Deletion

Nodes are of the form $n, c_0, (e_1, c_1), \dots, (e_n, c_n)$, where the e 's are the values or keys and the c 's are the pointers.

```
Procedure Delete(t,e) {
```

```
    // t points to root, and e will be deleted
```

```
    Search(t,x,P,found); // returns found=true if e in the tree
```

```
    // and P will point to the node in main memory that has e;
```

```
    // Returns false if e is not in the B-tree and P will point
```

```
    // to the last node visited (leaf node) during the search;
```

```
if found {  
    Let P point to node n, c_0, (e_1, c_1), ..., (e_n, c_n),  
        and e_i has value e;  
    if P->c_0 != 0 // P is not a leaf node  
    { Q = P->c_i; // Reads from Disk P->c_i and  
        // stores it in memory node Q  
        While Q is not a leaf node do  
            Q = Q->c_0; // Reads from Disk P->c_i and  
                // stores it in memory node Q  
        P->e_i = Q->e_1  
        Write P on Disk;  
        P = Q;  
        i = 1;  
    }
```

```

delete (P->e_i, P->c_i) from
    P: n,c_0,(e_1,c_1),...,(e_n,c_n)
    and replace P->n by P->n-1;
while (P->n < Ceil(m/2)-1) && (P != t) do
{ if P has a nearest right sibling Y
  {Let Z point to the parent of P and Y;
   Let j be such that Z->c_{j-1} == P && Z->c_j == Y;
   if Y->n >= ceil(m/2)
   { // can borrow from right sibling
     P->e_{P->n+1} = Z->e_j; //move from Z to P
     P->c_{P->n+1} = Y->c_0;
     P->n = P->n+1;
     Z->e_j = Y->e_1; //move e_1 from Y to Z
     Y->(n,c_0,(e_1,c_1),... ) =>
        Y->(n-1,c_1,(e_2,c_2),... ); //e_1 is deleted
     Output nodes P, Z & Y on Disk;
     return;
  }
}

```

```

    }

    //Has a right child but cannot borrow from it
    r = 2 Ceil(m/2)-2;
    // Borrow from parent and combine P and Y into one node
    Output ( r, P->c_0,(P->e_1,P->c_1),...,
            (P->e_{P->n},P->c_{P->n}),
            (Z->e_j,Y->c_0),
            (Y->e_1,Y->c_1),...,
            (Y->e_{Y->n},Y->c_{Y->n})) )
        as new node P;
    Node P is now node Z except that (Z->e_j,Z->c_j) is deleted;
}
else {do the nearest left sibling instead}
}
if P->n != 0 {Output P onto Disk;}
else { t = P->c_0; }
}

```

}

Extensions

- Above material from Horowitz and Sahni Fundamentals of DS (CS Press). But the algorithms were modified by Prof. Gonzalez to be more OO.
- A B' -Tree is like the B -Tree, but the values are at the failure nodes (instead of a null pointer we have a pointer to the data). Internal nodes have keys to direct the search. The Textbook [W] covers B' -Trees, but calls them B -Trees.
- B^* -Tree: The root has at least two children and at most $2\lceil(2m - 2)/3\rceil + 1$. Internal nodes have at least $\lceil(2m - 2)/3\rceil$ and at most m children. (Saves space).