# Hashing

- Table (hd) with D (or TableSize) entries or b (buckets).
- Hash function f(x) maps keys to  $\{0, 1, 2, ..., D-1\}$ , i.e., the universe is partitioned into D regions by the hash function.
- In the ideal situation the objects to be represented are mapped (via the hash function) to different positions in the hash table.
- Therefore, initialization takes O(D), and insert, delete and membership can be done in O(1) time (assuming the ideal situation).
- Most common hash function f(k) = k%D. f(k) gives the home bucket.



	•	Inser	t 24	(maj	ps to	2) do	oes n	ot ca	use a	,	
(	С	1	2 24	3 80	4 58	5	6	7 40	8	9	10 65
	• Insert 35 (maps to 2) causes a collision. So a ends up in position 5.										
(	С	1	2 24	3 80	4 58	5 35	6	7 40	8	9	10 65
• Insert 98 (maps to 10) causes a collision and ends up in position 0.											
( 98	0 8	1	2 24	3 80	4 58	5 35	6	7 40	8	9	10 65

## Search for x

- Begin at the home bucket till
  - You find the element (x is in the table), or
  - An empty spot (x is not in the table), or
  - Back at the home bucket (x is not in the table)

### Deletion

- Just erase the element will not work! (Like delete 80)
- Use a <u>NeverUsed bit</u> (and modify search and insert)

Performance (No Proofs for this part Discussed)

- Number of buckets is b = D.
- $\alpha = n/b$  is the load factor.
- Avg. Num. of buckets examined during unsuccessful searches  $U_n \sim \frac{1}{2} \left(1 + \frac{1}{(1-\alpha)^2}\right)$
- Avg. Num. of buckets examined during successful searches  $S_n \sim \frac{1}{2}(1 + \frac{1}{1-\alpha})$
- $\alpha = 0.5$  the  $U_n$  is 2.5 and  $S_n$  is 1.5.
- $\alpha = 0.9$  the  $U_n$  is 50.5 and  $S_n$  is 5.5.

D should be a prime or have no prime factors less than 20.

### Random Proving: Defn. & Analysis

- Overflow: Next bucket is found at random.
- Actually pseudo-random in order to be able to reproduce results.

Theorem 10.1 [Sa, Origin: Probability Theory]: Let p be the probability that certain event occurs. The expected number of independent trials needed for that event to occur is 1/p. Coin flips (for H or T): 2, and Die throw (for number in 1 - 6): 6.

- $\alpha = n/b$  is the load factor.
- Probability of an occupied bucket is  $\alpha$ .
- Probability that a bucket is empty is  $1 \alpha$ .
- Unsuccessful search: Looks for an empty bucket. Using independent trials the expected number of buckets examined is:

$$U_n \approx \frac{1}{1-\alpha}$$









• Bucket has a linked list of the keys that mapped to that bucket (inc. order)

```
0 -> 11 -> 33 -> 55 -> 66
1
2
3 -> 36 -> 69
4
5 -> 16 -> 49 -> 82
• plus infinity object at the end of the list
simplifies the code (Actually only one object).
0 -> 11 -> 33 -> 55 -> 66 -> BIG
1 -> BIG
2 -> BIG
3 -> 36 -> 69 -> BIG
```

- 4 -> BIG
- 5 -> 16 -> 49 -> 82 -> BIG

# Performance (No Proofs Discussed (See 10.5.4 in [Sa])

•  $\alpha = n/D$  is the load factor.

• Avg. Num. of nodes examined during successful searches  $S_n \sim 1 + \frac{\alpha}{2}$ 

• Avg. Num. of nodes examined during unsuccessful searches  $U_n \leq \alpha$ ,  $\alpha < 1$  $U_n \approx \frac{\alpha(\alpha+3)}{2(\alpha+1)}$ ,  $\alpha \geq 1$ 

### Text Compression: LZW

- Compress string aaabbbbbbbaabaaba, with  $\sum = \{a, b\}$
- "a" is assigned code 0 and "b" is assigned code 1.
- Mapping is stored in table
- 0 1 a b
  - Beginning with the above dictionary, find the longest prefix, p, of the un-encoded part of the input file that is in the dictionary and output its code.
  - If there is a next character c, in the input file then <u>pc</u> is assigned the next code and inserted in the dictionary.











5 37 The 5 implies that the fc is b So code 5 is 4b and added to the table 1 2 3 0 4 5 b 0a 2b 1b 4b a b aa aab bb bbb <-- extra line a The 5 outputs (bbb) The code 6 is 5\* 3 7 The 3 implies that the fc is a So code 6 is 5a and added to the table 1 2 3 4 5 0 6 b 0a 2b 1b 4b 5a a b aa aab bb bbb bbba <-- extra line а The 3 outputs (aab) The code 7 is 3\*



### Universal Hashing

- If the hash function is fixed in advance, then one can choose *n* keys so that all keys hash into the same place. So worst case may occur.
- Universal Hashing: Choose hash function randomly (independently of the hash keys being stored). Good performance on average.
- Ranodomized algorithms behave differently in each execution, even when the input is the same.
- Probability of a bad hash function is low.

- *H*: Finite collection of hash functions that map a given universe U of keys into the range {0, 1, ..., m − 1}.
- *H* is said to be *universal* if for each pair of distinct keys *x*, *y* ∈ *U*, the number of hash functions *h* ∈ *H* for which *h*(*x*) = *h*(*y*) is precisely | *H* | /*m*. In other words, with a hash function randomly chosen from *H*, the chance of a collision between *x* and *y* when *x* ≠ *y* is exactly 1/*m*, which is exactly the chance of a collision if *h*(*x*) and *h*(*y*) are randomly chosen from the set {0, 1, ..., *m* − 1}.



#### **Expected Number of Collisions**

- Theorem: If h is chosen from a universal collection of hash functions to map n keys to a table with m entries  $(n \le m)$ , the expected number of collisions involving a key x is less than one.
- Proof: Given y and z, let  $C_{yz}$  be a random variable equal to 1 if h(y) = h(z) and 0 otherwise.
- By definition (of universal hashing)  $E[C_{yz}] = 1/m.$
- Given x, let  $C_x$  be the total number of collisions involving key x in hash table T of size m with n keys.

• 
$$E[C_x] = \sum_{y \in T, y \neq x} E[C_{xy}] = (n-1)/m$$

• Since 
$$n \le m$$
, we know  $E[C_x] < 1$ .







