## Shadows


(a,

## One Slide Solution

* It is really very simple
* Can you see something from the eye position? Yes, then visible. No, then not visible (occluded)
* Can you see something from a light source position? Yes, then not in shadow. No, then in shadow
* If you know HLHSR, then do that from the light instead of the eye location


## Multiple Slides Solution

* But there can be multiple light sources
* The light source might not be a single point or a single direction (e.g., extended sources)
* Want to determine both visibility and lighting without multiple transforms


## Two-Pass Object Precision

* 1st pass: transform to light position
- hidden surface determination (polygons which are not in shadow)
* 2nd pass: transform to original world coordinate sys
apolygons not in shadow are merged to become surface detail polygons (which algorithm?)
* Postprocessing: transform to eye coordinate
a visible surface determination + surface details




## Two-pass Image Precision

* Z buffer from eye (e): what the viewer can see
$*$ Z buffer from light (1): what the light source can see
* for each (xe,ye,ze)
$\square$ transform to (xl,yl,zl)
$\square$ is zl more distant than $\mathrm{z}(\mathrm{xl}, \mathrm{yl})$
$>$ yes, (xe,ye) is in shadow
$>$ no, (xe,ye) is not in shadow

(a)


(b)

(e)

(c)

(f)



## Shadow Volume



## Shadow Volume

* Enclosed by
$\square$ (side) shadow polygons
$\square$ scene polygon
$\square$ back shadow polygon (scaled version of the original scene polygon)
* Shadow polygons are invisible and not rendered (used to determine whether an object is in shadow)
* SV polygons $=$ scene polygon + all shadow polygons


## Shadow Volume

$*$ From the viewer

- each front-facing (normal pointing to the viewer) SV polygon causes object to be in shadow
- each back-facing (normal pointing away from the viewer) SV polygon causes object to be out of shadow
- \#FF intersections >= \#BF intersections to be in shadow


## Shadow Volume

*How do you do this?

* A modified depth-sort type algorithm
a include SV polygons in the depth-sort list but process them front-to-back (instead of back-tofront)
$\square$ determine whether the eye is in any SV
$\square$ then count how many times the projection ray intersects FF and BF SV polygons
a easier said than done


## Soft Shadow



Fig. 16.48 Umbra and penumbra.

## Soft Shadow



## Using BSP Tree

* Stationary light source
* Stationary scene
* Moving camera
* Basic BSP tree algorithm
$\square$ Construct a tree based on scene polygons
$\square$ Determine rendering order
* Enhancement
- Polygons need surface details for right order and appearance
- Order is taken care of by basic BSP
$\square$ How about surface details?


## Intuition

* Surface details (in shadow or not) are stationary regardless of camera position
$\square$ Find once
$>$ if a polygon is in shadow or not, and
> Which part is in shadow (surface detail polygons)
* Which polygon is NOT in shadow
- The one that is closet to the light source
* The polygon $2^{\text {nd }}$ closest to the light source can only have shadow from the closet polygons
* The polygon $3^{\text {rd }}$ closest to the light source can only have shadow from the $1^{\text {st }}$ and $2^{\text {nd }}$ closet polygons, etc.


## SVBSP Tree

* A binary tree
* Each node is a $S V$ polygon (instead of a scene polygon)
* Space is divided into IN/OUT by a node (a SV polygon, normal pointing out)
* Leaf nodes are labeled IN/OUT






## SVBSP Tree Construction

* Ordering is important
$\square$ the polygon which is closest to the light source must be used first
$\square$ the polygon which is 2 nd closest to the light source then filtered down the SVBSP tree to generate surface details polygons
$\square$ add the 2nd closest polygons to SVBSP tree
$\square$ the polygon which is 3 rd closest to the light source then filtered down the SVBSP tree to generate surface details polygons
$\square$ add the 3rd closest polygons to SVBSP tree -...
* How to know which polygon is closest (2nd, 3rd closest ....) to the light source?
* Use the regular BSP Tree
$\square$ traverse according to the light source position
$>$ first the half containing light
$>$ then the partition plane
$>$ then the half not containing light
* First pass (SVBSP): surface details
* Second pass (BSP): eye locations for rendering


## Other Possibilities

* Ray Tracing
a with shadow rays to the sources
* Radiosity
a with form factor computation
* Later


## Fake Shadow

* Shadow generation is not trivial
$\square$ OpenGL does not do it
* Reason
$\square$ Shading calculation can be based entirely on "local" information, while shadow calculation cannot (need to know the relative position of many objects)
* In reality
$\square$ Shadow does not to be entirely correct, it just has to be realistic


## Fake Shadow (cont.)

* Usually, in an indoor environment
$\square$ Light is on the ceiling
$\square$ Walls and floor enclose the scene (and they are planar)
$\square$ Cast shadows on those enclosing surfaces by projecting objects onto them



## Example

*Figure out the projection transform From ( $\mathrm{x}, \mathrm{y}, \mathrm{z}, 1$ ) to (i,j,1)

* Apply this transform to all scene polygons
*. Draw projected polygons in dark (shadow) colors


## Math

$$
\begin{aligned}
& \text { line }\left\{\begin{array}{l}
x=l_{x}+t\left(p_{x}-l_{x}\right) \\
y=l_{y}+t\left(p_{y}-l_{y}\right) \\
z=l_{z}+t\left(p_{z}-l_{z}\right) \\
z=0
\end{array}\right. \\
& \text { plane } \begin{array}{c}
z= \\
\Rightarrow l_{z}+t\left(p_{z}-l_{z}\right)=0
\end{array} \\
& \Rightarrow t=-\frac{l_{z}}{\left(p_{z}-l_{z}\right)} \\
& \Rightarrow x=\frac{l_{z} p_{x}-l_{x} p_{z}}{\left(p_{z}-l_{z}\right)}, y=\frac{l_{z} p_{y}-l_{y} p_{z}}{\left(p_{z}-l_{z}\right)} \\
& {\left[\begin{array}{c}
x \\
y \\
1
\end{array}\right]=\left[\begin{array}{cccc}
l_{z} & 0 & -l_{x} & 0 \\
0 & l_{z} & -l_{y} & 0 \\
0 & 0 & 1 & -l_{z}
\end{array}\right]\left[\begin{array}{c}
p_{x} \\
p_{y} \\
p_{z} \\
1
\end{array}\right]} \\
& \text { Computer Graphics }
\end{aligned}
$$

